

Instruction handbook

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be in motion **be in motion**



b maXX 5000

Add-on modules

**Incremental encoder emulation
IEE**

**SSI encoder emulation
SIE**

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Table of Contents

1	General	5
1.1	Information on this Instruction Handbook	5
1.2	Key to symbols	6
1.3	Limitation of liability	7
1.4	Copyright protection	7
1.5	Other applicable documents	7
1.6	Spare parts	8
1.7	Disposal	8
1.8	Guarantee provisions	8
1.9	Customer service	8
1.10	Used terms	8
1.11	List of associated documentations	9
2	Safety	11
2.1	Contents of the Instruction Handbook	11
2.2	Changes and modifications to the device	11
2.3	Use, compliant with intended purpose	12
2.4	Responsibility of the operating company	12
2.5	Training of the personnel	13
2.6	Special hazards	14
2.7	Fire fighting	15
2.8	Safety equipment	16
2.9	Behavior in hazardous situations or at accidents	16
2.10	Signs and labels	17
3	Technical Data	19
3.1	Operation conditions	19
3.2	Electrical data	20
3.2.1	IEE - Incremental encoder emulation, 2 channels	20
3.2.2	SIE - SSI encoder emulation, 2 channels	22
4	Design and Operation	25
4.1	Design	25
4.2	Add-on module IEE	27
4.3	Add-on module SIE	28
4.4	Identification of the device	29
4.4.1	Part number	29
4.4.2	Type plate	30
4.4.3	Type code	31
4.4.4	Danger areas	31
4.5	Display and operation elements	32
5	Installation	33
5.1	Safety notes	33
5.2	Demands on the power supply	34
5.3	Requirements to the connection cables	34
5.4	Installation IEE	35
5.4.1	Connection diagram IEE	35
5.4.2	Installation procedure IEE	36
5.4.3	Pin assignment IEE	36
5.4.4	Connecting cable IEE	37



Table of Contents

5.5	Installation SIE	38
5.5.1	Connection diagram SIE	38
5.5.2	Installation procedure SIE	39
5.5.3	Pin assignment SIE	39
5.5.4	Connecting cable SIE	40
6	Commissioning/Operation	43
6.1	Safety notes	43
6.2	Commissioning procedure IEE	44
6.2.1	Recognition of the incremental encoder emulation IEE	44
6.2.2	Parameter setting IEE	47
6.2.3	Function test IEE	48
6.3	Commissioning procedure SIE	53
6.3.1	Recognition of the SSI encoder emulation SIE	53
6.3.2	Parameter setting SIE	56
6.3.3	Function test SIE	57
7	Troubleshooting and fault correction	59
7.1	Behavior in case of malfunctions	59
7.2	Error detection	60
7.3	Error handling	61
7.3.1	Quit errors	61
7.3.2	Error messages	62
	Table of Figures	65
	Index	67
	Survey of Revisions	69

GENERAL

1.1 Information on this Instruction Handbook

The manual **b maXX 5000 add-on module IEE/SIE** is an addition to the Instruction handbook **b maXX 5000** (5.09021) or **b maXX 5500** (5.13008) for devices with

incremental encoder emulation

type code: BM5XXX-XXXX-XX**01** and

SSI encoder emulation

type code: BM5XXX-XXXX-XX**03**.

The basic prerequisite for safe working is compliance with all the safety and handling instructions stated in the instruction handbooks **b maXX 5000** or **b maXX 5500**.

Additionally, the valid accident prevention regulations and general safety regulations applicable to the scope of application the device must be complied with.

Read this Instruction handbook and the Instruction handbooks **b maXX 5000** or **b maXX 5500**, particularly the safety notes chapter, completely before beginning any work on the device. This Instruction handbook is part of the product and must be kept accessible to personnel at all times in the immediate vicinity of the device.

1.2 Key to symbols

Warning notes

Warning notes are identified by symbols in this Instruction handbook. The notes are introduced by signal words that express the extent of the danger.

It is imperative that these notes be complied with and are conscientiously regarded in order to prevent accidents, personal injury and material damage.



DANGER!

....this indicates a hazardous situation which, if not avoided, will result in death or serious injury.



WARNING!

....this indicates a hazardous situation which, if not avoided, could result in death or serious injury.



CAUTION!

....this indicates a hazardous situation which, if not avoided, could result in minor or moderate injury.



NOTICE!

....indicates a hazardous situation which, if not avoided, may cause material damage.

Recommendations



NOTE!

....highlights useful hints and recommendations, as well as information for the efficient and trouble-free use.

1.3 Limitation of liability

All specifications and notes in these instruction handbook were compiled taking into account the applicable standards and regulations, the state of the art and our knowledge and experience of many years.

The manufacturer assumes no liability for damages due to:

- non-compliance with the instruction handbook
- usage for other than the intended purpose
- usage by untrained personnel

The actual scope of delivery can vary in case of optional equipment, laying claim to additional order options, or on account of the latest technical changes to the explanations and representations described herein.

The user bears the responsibility for performing service and initial operation in accordance with the safety regulations of the applicable standards and all other relevant governmental or local regulations concerning the dimensioning and protection of conductors, grounding, disconnectors, overcurrent protection, etc.

The person who carried out the mounting or installation is liable for any damage incurred when assembling or connecting the device.

1.4 Copyright protection

The instruction handbook must be treated confidentially. It is to be used exclusively by personnel who work with the device. The consignment of the instruction handbook to third persons without the written permission of the manufacturer is prohibited.



NOTE!

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1.5 Other applicable documents

Components of other manufacturers are integrated into the device. For these purchased parts, hazard assessments have been performed by the respective manufacturers. The compliance of the design construction with the applicable European and national regulations has been declared for the components by the respective manufacturers.

1.6 Spare parts



WARNING!

False or flawed spare parts can lead to damage, malfunction or complete failure, thus endangering safety.

Therefore:

- Only use original spare parts of the manufacturer.

Procure spare parts through an authorized dealer or directly from the manufacturer.

1.7 Disposal

Insofar as no take-back or disposal agreement has been made, please disassemble units correctly and properly recycle the constituent parts.

See also **b maXX 5000** 5.12008, chapter Disposal.

1.8 Guarantee provisions

The guarantee provisions are stated in a separate document of the sales documents.

The devices described herein may only be operated in accordance with the stipulated methods, procedures and conditions. Anything else not presented here, including the operation of devices in mounted positions, is not permitted and must be cleared with the plant on a case-by-case basis. If the devices are operated in any other manner than as described within this Instruction handbook, then all guarantee and warranty rights are rendered null and void.

1.9 Customer service

Our customer service is available to provide you with technical information.

Info on the responsible contact persons is available at all times via telephone, fax, mail or the Internet.

1.10 Used terms

A list of the abbreviations used can be found in **b maXX 5000** (5.09021) or **b maXX 5500** (5.13008), Appendix A: Abbreviations.

1.11 List of associated documentations

Instruction Handbook

	Doc No.	Part No. German	Part No. English
Instruction handbook b maXX 5000	5.09021	439682	439683
Instruction handbook b maXX 5500	5.13008	446683	446684

Parameter Manual

	Doc No.	Part No. German	Part No. English
Parameter Manual b maXX 5000	5.09022	428331	431082

Instruction Handbooks Add-on modules

	Doc No.	Part No. German	Part No. English
Add-on module incremental encoder emulation IEE SSI encoder emulation SIE	5.13030	448189	448190

SAFETY

This section provides an overview of all of the important safety aspects for optimum protection of personnel as well as for the safe and problem-free operation.

2.1 Contents of the Instruction Handbook

Each person who is tasked with performing work on or with the device must have read and understood this Instruction Handbook and the Instruction Handbook of **b maXX 5000** (5.09021) or **b maXX 5500** (5.13008) before working with the device. This also applies if the person involved with this kind of device or a similar one, or has been trained by the manufacturer.

2.2 Changes and modifications to the device

In order to prevent hazards and to ensure optimum performance, no changes, additions or modifications may be undertaken on the device that have not been explicitly approved by the manufacturer.

2.3 Use, compliant with intended purpose

2.3 Use, compliant with intended purpose

The **incremental encoder emulation IEE** or **SSI encoder emulation SIE** is considered as being used compliant with its intended purpose if all notes and information of this Instruction handbook and the Instruction handbook **b maXX 5000** (5.09021) or **b maXX 5500** (5.13008) are adhered to.



WARNING!

Danger arising from usage for an unintended purpose!

Any usage that goes beyond the intended purpose and/or any non-compliant use of the device can lead to dangerous situations.

Therefore:

- Only use the device compliant with its intended purpose.
- Note all specifications of this Instruction handbook and the Instruction handbook **b maXX 5000** 5.12008.
- Ensure that only qualified personnel work with/on this device.
- When configuring, ensure that the device is always operated within its specifications.
- The device may only be operated in a technically flawless condition.
- Only operate the device in combination with components approved by Baumüller Nürnberg GmbH.

2.4 Responsibility of the operating company

The device will be used in commercial areas. Thus, the proprietor of the device is subject to the legal work safety regulations.

Along with the notes on work safety in this Instruction handbook and the Instruction handbooks **b maXX 5000** (5.09021) or **b maXX 5500** (5.13008) the safety, accident prevention and environmental protection regulations valid for the area of application of this device must be complied with. Whereby:

- The operating company must inform himself about the applicable work health and safety regulations and ascertain, in a hazard assessment, any additional hazards that could arise from the special working conditions in the use area of the device. These must then be implemented in the form of operating instructions for operation of the device.
- This Instruction handbooks must be kept accessible to personnel working with the device at all times in the immediate vicinity of the device.
- The specifications of the Instruction handbooks must be adhered to completely and without exception.
- The device may only be operated in a technically faultless and operationally safe condition.

2.5 Training of the personnel

**WARNING!****Risk of injury due to insufficient qualifications!**

Improper handling can lead to significant personal injury and material damage.

Therefore:

- Certain activities can only be performed by the persons stated in the respective chapters of this Instruction handbook.

In this Instruction handbook, the following qualifications are stipulated for various areas of activity:

- **Operating personnel**

- The drive system may only be operated by persons who have been specially trained, familiarized and authorized.
- Troubleshooting, maintenance, cleaning, maintenance and replacement may only be performed by trained or familiarized personnel. These persons must be familiar with the Instruction handbook and act accordingly.
- Initial operation and familiarization may only be performed by qualified personnel.

- **Qualified personnel**

- Electrical engineers authorized by Baumüller Nürnberg GmbH, and qualified electricians of the customer or a third party who have learned to install and maintain Baumüller drive systems and are authorized to ground and identify electrical power circuits and devices in accordance with the safety engineering standards of the company.
- Qualified personnel have had occupational training or instruction in accordance with the respective locally applicable safety engineering standards for the upkeep and use of appropriate safety equipment.

2.6 Special hazards

In the following section, the remaining marginal risks will be stated that have been identified as a result of the hazard analysis.

Observe the safety notes listed here and the warning notes in the further chapters of this manual to reduce health risks and dangerous situations.

Electrical current



DANGER!

Risk of fatal injury from electrical current!

There is an immediate risk of fatal injury if live electrical parts are contacted. Damage to the insulation or individual components can be life-threatening.

Therefore:

- Switch off the electrical power immediately in case of damage to the power supply insulation.
- Only allow work on the electrical system to be performed by qualified personnel.
- Switch off the current when any kind of work is being performed on the electrical system and ensure safety before switching on again.

Danger from residual energy



DANGER!

Risk of fatal injury from electrical current!

Stored electric charge.

Discharge time of the system = discharge time of the device with the longest DC link discharge time connected to the DC link.

See Instruction handbook **b maXX 5000** 5.12008, chapter Electrical Data.

Therefore:

- Do not touch electrically live parts before taking into account the discharge time of the capacitors.
- Pay attention to the corresponding notes on the device.
- If additional capacitors are connected to the DC link, the DC link discharge can take a much longer time. In this case, the necessary waiting period must itself be determined or a measurement made as to whether the equipment is de-energized. This discharge time must be posted, together with an IEC 60417-5036 (2002-10) warning symbol, on a clearly visible location of the control cabinet.

Moving components



WARNING!

Risk of injury from moving components!

Rotating components and/or components moving linearly can result in severe injury.

Therefore:

- Do not touch moving components during operation.
- Do not open any covering during operation.
- The amount of residual mechanical energy depends on the application. Powered components still turn/move for a certain length of time even after the power supply has been switched off. Ensure that adequate safety measures are taken.

2.7 Fire fighting



DANGER!

Risk of fatal injury from electrical current!

There is a risk of electric shock if an electrically-conductive, fire-extinguishing agent is used.

Therefore:

- Use the following fire-extinguishing agent:



ABC powder / CO₂

2.8 Safety equipment



WARNING!

Risk of fatal injury due to non-functional safety equipment!

Safety equipment provides for the highest level of safety in a facility. Even if safety equipment makes work processes more awkward, under no circumstances may they be circumvented. Safety can only be ensured by intact safety equipment.

Therefore:

- Before starting to work, check whether the safety equipment is in good working order and properly installed.

2.9 Behavior in hazardous situations or at accidents

Preventive measures

- Always be prepared for accidents or fire!
- Keep first-aid equipment (e.g. first-aid kits, blankets, etc.) and fire extinguishers readily accessible.
- Familiarize personnel with accident signalling systems, first aid equipment and life saving equipment.

And if something does happen: respond properly.

- Stop operation of the device immediately with an EMERGENCY Stop.
- Initiate first aid measures.
- Evacuate persons from the danger zone.
- Notify the responsible persons of the site.
- Alarm medical personnel and/or the fire department.
- Keep access routes clear for rescue vehicles.

2.10 Signs and labels

The following symbols and information signs are located in the working area. They refer to the immediate vicinity in which they are affixed.

**WARNING!****Risk of injury due to illegible symbols!**

Over the course of time, stickers and symbols on the device can become dirty or otherwise unrecognizable.

Therefore:

- Maintain all safety, warning and operating labels on the device in easily readable condition.

**Electrical voltage**

Only qualified personnel may work in work areas that identified with this.

Unauthorized persons may not touch working materials marked correspondingly.

**DANGER!****Risk of fatal injury from electrical current!**

See ►[Danger from residual energy](#)◄ auf Seite 14.

**CAUTION!****Risk of injury due to hot surface!**

Therefore:

- Wear protective gloves



TECHNICAL DATA

3.1 Operation conditions

The operation conditions of **b maXX 5000** are valid, see Instruction Handbook **b maXX 5000** (5.09021) or **b maXX 5500** (5.13008).

Transport temperature range	- 25 °C to + 70 °C
Transport climatic class EN 60721-3-2	2 K 3
Storage temperature range	- 25 °C to + 55 °C
Storage climatic class EN 60721-3-1	1 K 4



NOTICE!

Normally, non-conductive pollution occurs. Conductive pollution is unacceptable. Conductive pollution can lead to the destruction of the device. The customer is responsible for destructions, which were caused by pollution due to conductive materials or components.

3.2 Electrical data

3.2.1 IEE - Incremental encoder emulation, 2 channels

Supply voltage (external supply)	5 V \pm 5 % (without load)
Supply current (external supply)	max. 100 mA (without load)
Signal level: output high voltage at $I_{OH} = - 20$ mA	2.5 V
Signal level: output high voltage at $I_{OL} = + 20$ mA	0.5 V
Output frequency, track signals	max. 500 kHz
Switching time: rising time	< 50 ns
Switching time: dropping time	< 50 ns
Delay time	$ t_d \leq 50$ ns
Power input	0.525 W
Current output driver	max. 15 mA

The mentioned timings are available at the module output. When selecting a cable in order to transmit the signals to an adequate evaluation unit, it must be considered, that a real cable can reduce the maximum transferable output frequency by its attenuation (change of specified signal performance).

An „adequate evaluation unit“ is an unit, which is able to sense even the smallest possible track signal changes without mistakes. The incremental encoder emulation IEE was developed in such a way, that even the smallest position variations or the encoder evaluation noise are converted into track signals. If the evaluation unit is not applicable, it can possibly occur, that the actual encoder signal varies by 1 bit, although the position is kept. The evaluation electronic then adds the variations only in one direction (because it is not in a position to sense quick changes in a correctly manner) and for the connected control the position appears like a slow drifting.

TTL square wave pulse cycles

Two TTL square wave pulse cycles A and B with a 90° electrical phase shifting and their inverted pulse cycles A and B as also a zero pulse 0 with the inverted signal 0 are available by way of output signals.

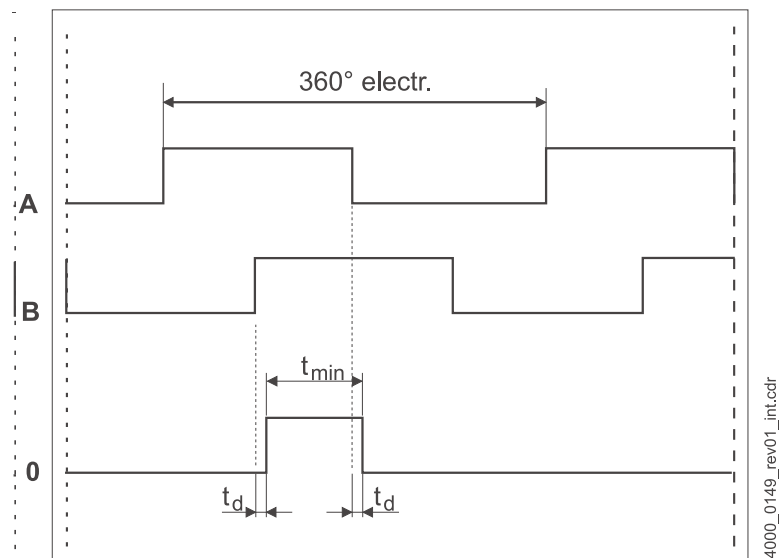


Figure 1: Pulse cycles, incremental encoder emulation IEE

3.2.2 SIE - SSI encoder emulation, 2 channels

Supply voltage (internal supply)	5 V \pm 5 %
Supply current (internal supply)	max. 60 mA
Signal level	RS485
Clock frequency min.	min. 200 kHz
Clock frequency max.	max. 2 MHz
Power input	0.525 W
Current output driver	max. 15 mA
Terminating resistor (internal)	120 Ω

The mentioned timings are available at the module output. When selecting a cable in order to transmit the signals to an adequate evaluation unit, it must be considered, that a real cable can reduce the maximum transferable output frequency by its attenuation (change of specified signal performance).

Timing diagrams of data transmission

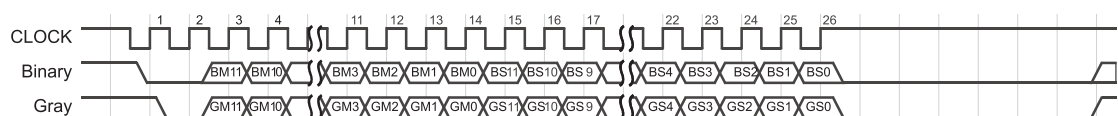


Figure 2: Timing diagram 12/12 no parity

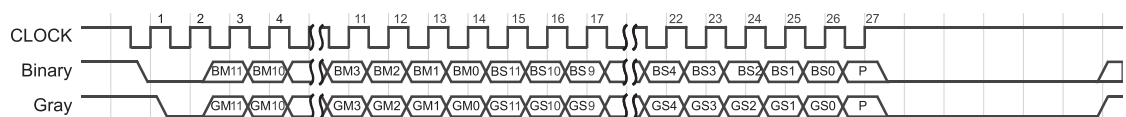


Figure 3: Timing diagram 12/12 parity

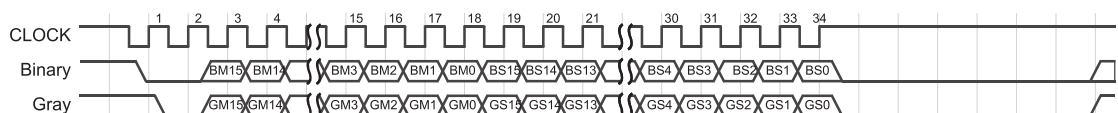


Figure 4: Timing diagram 16/16 no parity

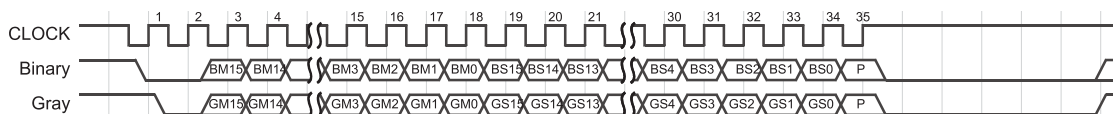


Figure 5: Timing diagram 16/16 parity

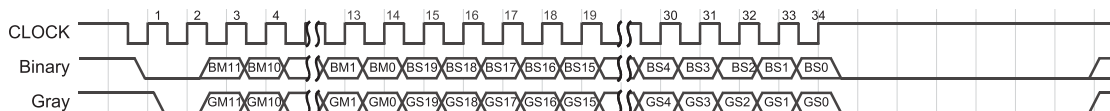


Figure 6: Timing diagram 12/20 no parity

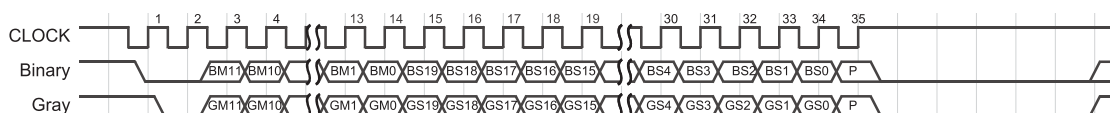


Figure 7: Timing diagram 12/20 parity

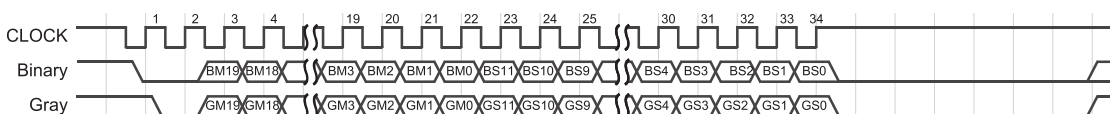


Figure 8: Timing diagram 20/12 no parity

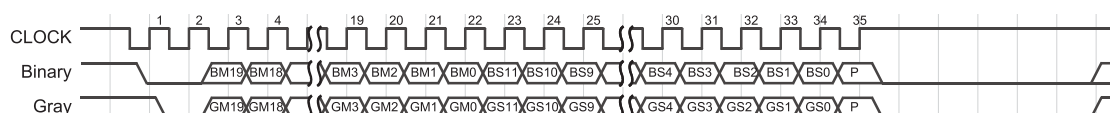


Figure 9: Timing diagram 20/12 parity

DESIGN AND OPERATION

4.1 Design

The **b maXX. 5000** series consists of an (active) mains rectifier unit and one or more axis units or a basic unit with/without axis units. The possible number of axis units depends on the connected load of the DC link of the mains rectifier unit.

b maXX 50XX

Mains rectifier unit

This is a mains rectifier unit for supplying axis units via the DC link.

The applied AC voltage at the three phase power system is transformed by a rectifier on the input side into DC voltage. The DC link capacitors smooth this DC voltage.

b maXX 51XX

Active mains rectifier unit

This is an active mains rectifier unit for supplying axis units via the DC link.

The applied AC voltage at the three phase power system is transformed by a rectifier on the input side into DC voltage. The DC link capacitors smooth this DC voltage. The active mains rectifier unit can feed back excess braking energy into the mains as sinusoidal electrical current.

b maXX 53XX

Single axis unit safety, double axis unit safety

This is a motor inverter that is supplied from the DC link via a mains rectifier unit or active mains rectifier unit.

From the DC voltage at the DC link, the inverter on the output side produces a three-phase current system with variable frequency and voltage for feeding the connected motor.

b maXX 55XX

b maXX 55XX are universal units, for achieving electrical drives in industrial applications. **b maXX 55XX** offers the largest configuration possibilities as well as the most available options.

b maXX 56XX

b maXX 56XX (acceleration units) are especially developed servo drives derived from **b maXX 55XX** for acceleration applications. Characteristic for these devices is, that the peak current is twice as large as the rated current, even at large output currents. The devices were developed for a cycle, which could provide the peak current for 1.25 s at a whole cycle duration of 5 s.

b maXX 57XX

b maXX 57XX (continuous current units) are servo converters especially developed for main drives, derived from **b maXX 55XX**. The devices were developed to maximize the available rated current by water cooling. For this reason these devices are only available with water cooling (cooling type -F and -Z) and with none peak current (only **b maXX 5773** with low peak current).



NOTE!

Proper operation of the **b maXX axis units BM53XX** can only be ensured with Baumüller **mains rectifier units BM50XX, BM51XX** or **basic units BM4XXX / BM5XXX**.

Controller

The controller unit controls the inverter of the power unit. The controller is operated either by means of operating software or by means of a higher-level control unit.

The incremental encoder emulation IEE is implemented in devices with type code: **BM5XXX-XXXX-XX01**.

The SSI encoder emulation SIE is implemented in devices with type code: **BM5XXX-XXXX-XX03**.

4.2 Add-on module IEE



NOTE!

Only devices with type code BM5XXX-XXXX-XX**01** provide the add-on module incremental encoder emulation!

The module is built-in and cannot be changed.
It is forbidden to remove the yellow front cover.

The incremental encoder emulation provides 2 channels (output X1 and X2).

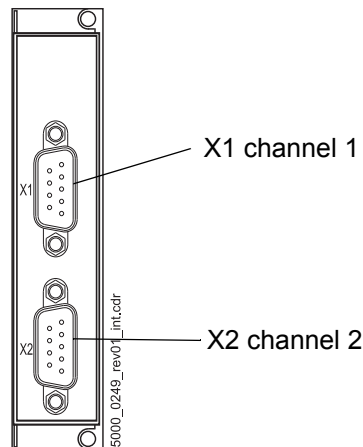


Figure 10: Front view add-on module IEE

Set values for the incremental encoder emulation can be obtained from the sources given below:

- Position actual values encoder 1 or encoder 2, see examples 1 and 2 in [►Figure 14◄](#) on page 35
- Position actual values (e. g. internal from positioning)
- Field bus set value (external set via bus), see example 3 in [►Figure 14◄](#) on page 35.

The signal generated can either be used for synchronization of the following axis, see examples 1 and 3 in [►Figure 14◄](#) on page 35 or for position measuring of the axis by a master control, see example 2 in [►Figure 14◄](#) on page 35.

4.3 Add-on module SIE



NOTE!

Only devices with type code BM5XXX-XXXX-XX**03** provide the add-on module SSI encoder emulation!

The module is built-in and cannot be changed.
It is forbidden to remove the yellow front cover.

The SSI encoder emulation provides 2 channels (output X1 and X2).

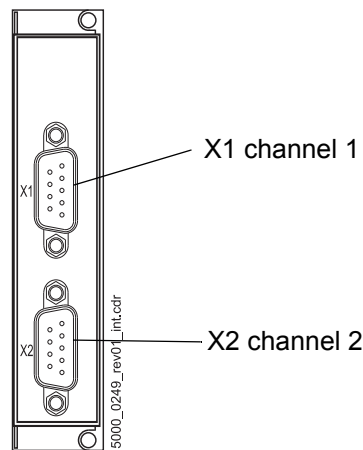


Figure 11: Front view add-on module SIE

Set values for the SSI encoder emulation can be obtained from the sources given below:

- Position actual values encoder 1 or encoder 2, see examples 1 in [▶Figure 16◀](#) on page 38
- Position actual values (e. g. internal from positioning)

The generated signal can be used for position measuring of the axis by a master control, see example 2 in [▶Figure 16◀](#) on page 38.

4.4 Identification of the device

4.4.1 Part number

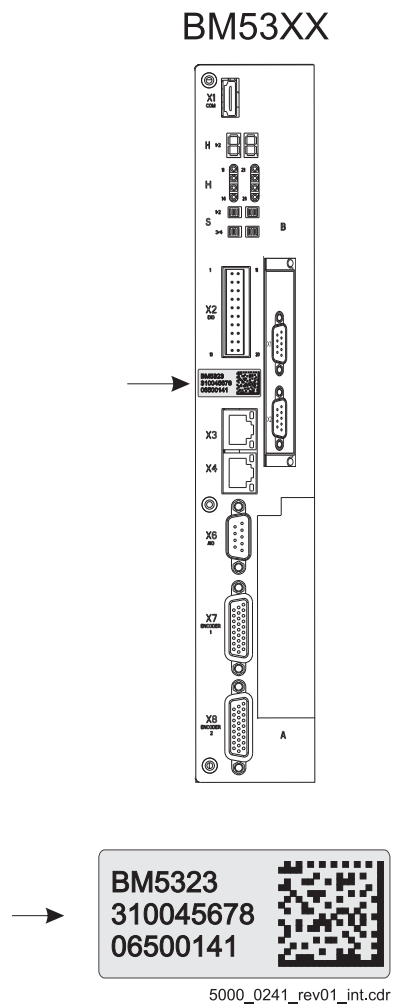


Figure 12: Part number - front

4.4 Identification of the device

4.4.2 Type plate

Examples of the locations where the type plate is affixed are shown in the figure. Among other things, the type plate also shows the type code of the device.

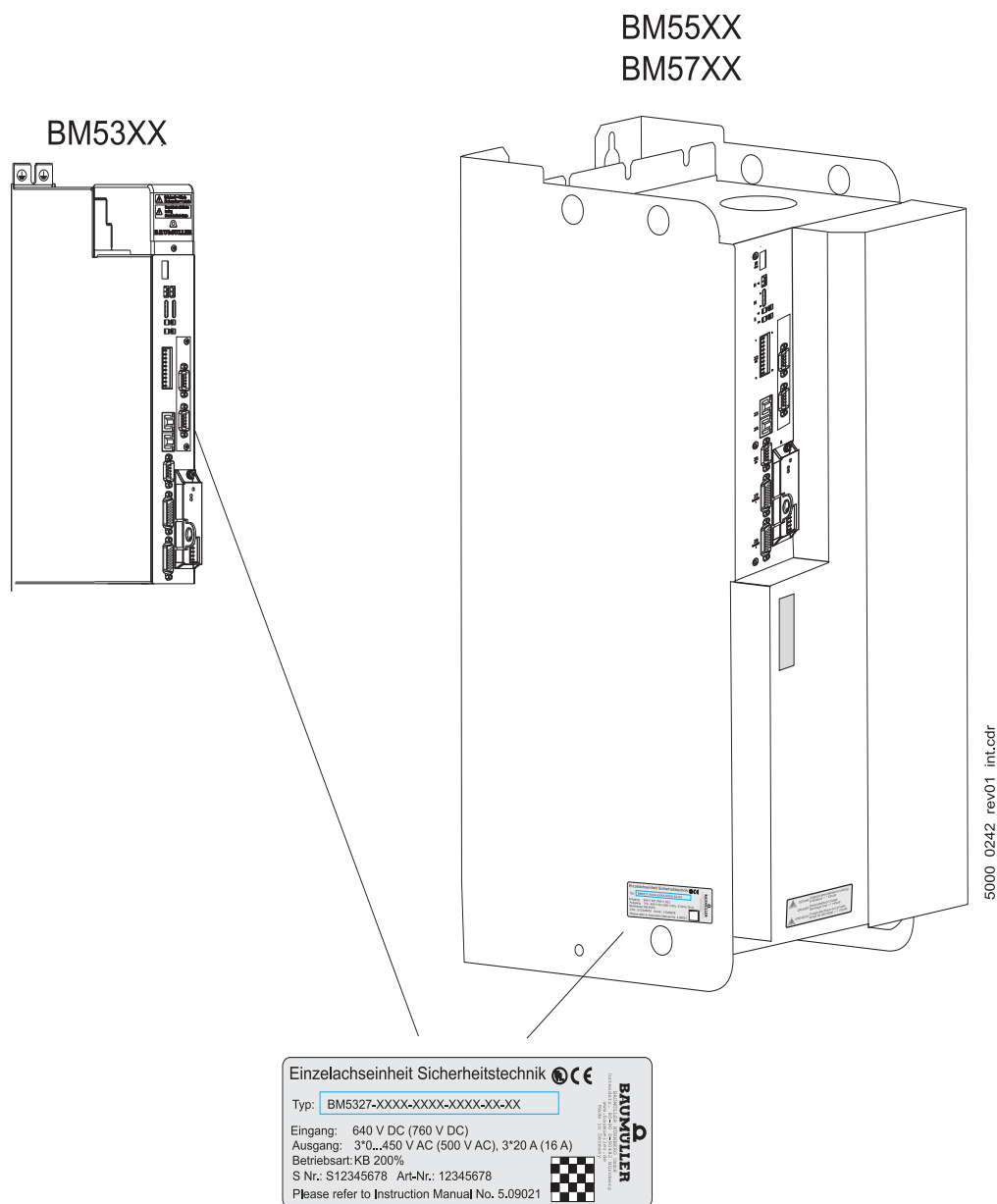


Figure 13: Location of the type plate

4.4.3 Type code

The type code has the format: BM5XXX - XXXX - XXXX - XXXX - XX - XXXX.

BM5XXX-XXXX-XXXX-XXXX-XX-XXXX	Device generation
BM5XXX-XXXX-XXXX-XXXX-XX-XXXX	Device design
BM5XX-XX-XXXX-XXXX-XXXX-XX-XXXX	Housing size
BM5XXX-XX-XXXX-XXXX-XXXX-XX-XXXX	Current stages (output rated current)
BM5XXX-XXXX-XXXX-XXXX-XX-XXXX	Type of cooling
BM5XXX-XX-XX-XXXX-XXXX-XX-XXXX	Type of mains
BM5XXX-XX-XX-XXXX-XXXX-XX-XXXX	Safety relay
BM5XXX-XXX-XX-XXXX-XXXX-XX-XXXX	Power unit design
BM5XXX-XXXX-XX-XX-XXXX-XX-XXXX	Encoder evaluation
BM5XXX-XXXX-XX-XX-XXXX-XX-XXXX	Add-on module 00: without module 01: Option module IEE with external power supply 03: Option module SIE with internal power supply
BM5XXX-XXXX-XXXX-XX-XX-XX-XXXX	Fieldbus configuration
BM5XXX-XXXX-XXXX-XX-XX-XX-XXXX	Hardware configuration controller
BM5XXX-XXXX-XXXX-XX-XX-XX-XXXX	Design
BM5XXX-XXXX-XXXX-XX-XX-XX-XXXX	Controller software version



NOTE!

Only devices with type code BM5XXX-XXXX-XX**01** provide the add-on module incremental encoder emulation IEE!

Only devices with type code BM5XXX-XXXX-XX**03** provide the add-on module SSI encoder emulation SIE!



NOTE!

Only the operation with ProDrive is described. If the software is not available, please contact Baumüller Nürnberg GmbH or visit our Website www.baumueller.com for download.

4.4.4 Danger areas

Please observe the safety notes in instruction manuals **b maXX 5000** or **b maXX 5500**.

4.5 Display and operation elements

The add-on module **incremental encoder emulation IEE** or **SSI encoder emulation SIE** has no display or operation elements.

The LED H14 and H24 of **b maXX 5000** / **b maXX 5500** respectively the emulation of the LED in ProDrive displays all device errors, even the errors occurring in connection with the add-on modules **IEE** or **SIE**.

INSTALLATION

This chapter describes the electrical installation of the **b maXX 5000** add-on module **IEE/SIE**.

5.1 Safety notes



DANGER!

Risk of fatal injury from electrical current!

Inevitably, when operating this electrical device, certain parts of it are energized with hazardous voltage.

Therefore:

- Pay heed to areas on the device that could be dangerous during the electrical installation.
- Pay heed to areas on the device that could still be electrically energized after operation.



WARNING!

Danger because of faulty installation and initial commissioning!

Installation and commissioning require qualified personnel with adequate experience. A installation fault can cause danger situations or large damage of property.

Therefore:

- Only personnel from manufacturer or qualified personnel operate while installation and initial commissioning

5.2 Demands on the power supply

5.2 Demands on the power supply

In order to comply with the standard EN 60 204-1 (electrical equipment of machines), the cable specified therein must be used. The connecting plugs must not drop - otherwise there is a danger of short circuits, external voltage, etc.



NOTICE!

The danger is: **electrical voltage**.

- 1 Ensure that the electrical power connection parameters as specified in the Technical Data are adhered to and that the connections are made in accordance with the stipulated data.
- 2 Avoid short circuit between input and output points.



NOTE!

Pay attention to EMC compatible cabling, see instruction handbook **b maXX 5000** or **b maXX 5500**, chapter [Installation requirements with regard to EMC](#).

5.3 Requirements to the connection cables

Completely assembled cables are not available, assembly of a connection cable see [►Connecting cable IEE◄](#) from page 37 or [►Connecting cable SIE◄](#) from page 40.

5.4 Installation IEE

5.4.1 Connection diagram IEE

Example 1

- Set value IEE from encoder
- Signal IEE to following axis

Example 2:

- Set value IEE from encoder
- Signal IEE to master control

Example 3:

- Set value IEE from master control
- Signal IEE to following axis

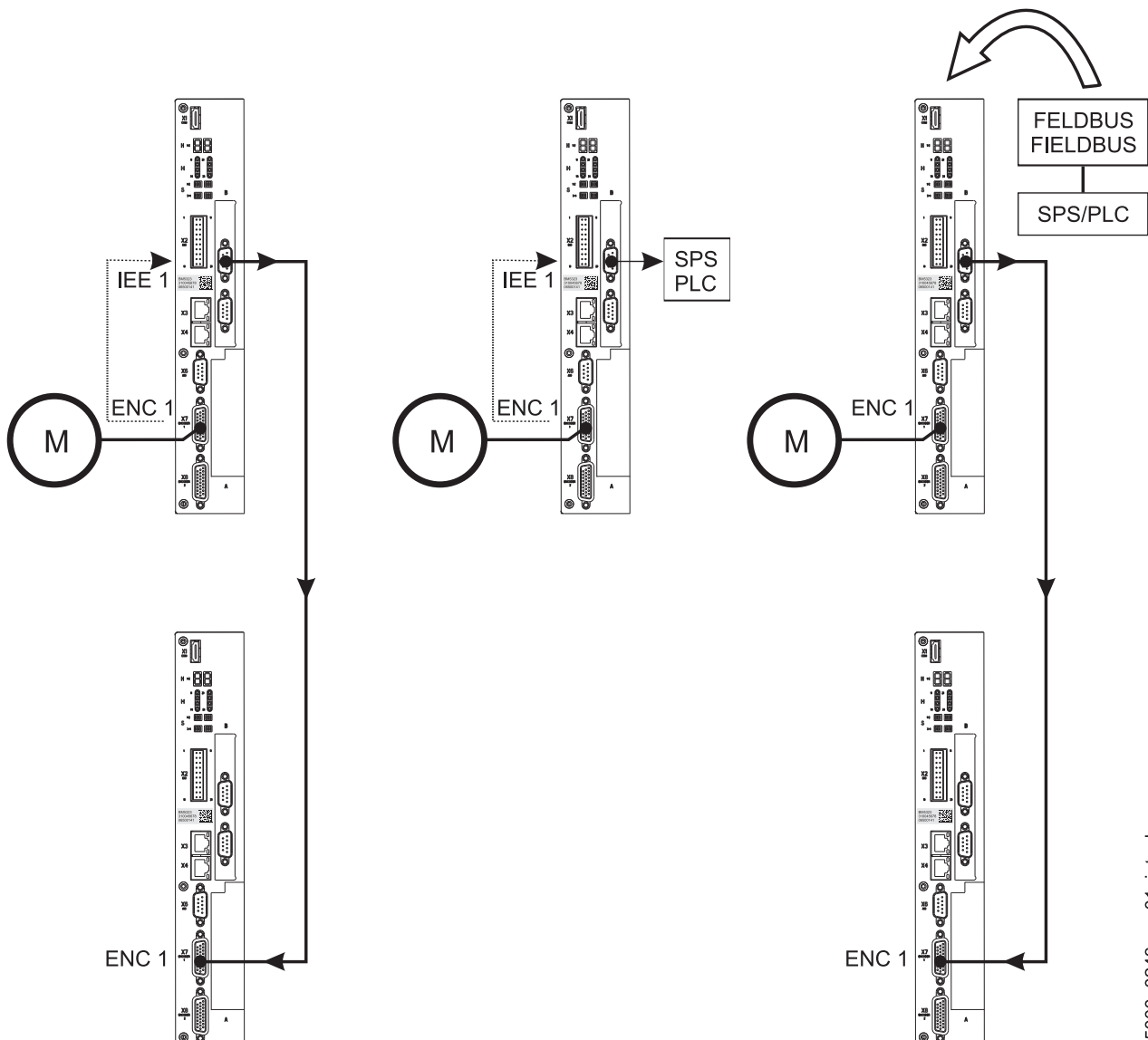


Figure 14: Connection diagram incremental encoder emulation IEE

5000_0243_rev01_int.cdr

5.4 Installation IEE

5.4.2 Installation procedure IEE

Depending on the desired application you now are able to connect the incremental encoder emulation with further system components (see ►Figure 14◄ on page 35).

- 1 Make sure that the **b maXX 5000** has been switched off voltage.
- 2 Connect an output (e.g. X1) of the incremental encoder emulation IEE with the encoder input of the higher-level control (see example 2 in ►Figure 14◄ on page 35).
Pin assignment see ►Pin assignment IEE◄ on page 36,
Cable see ►Connecting cable IEE◄ on page 37;

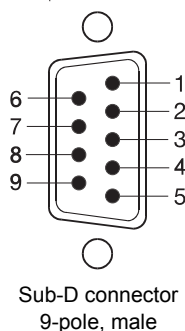
or

- 3 Connect an output (e.g. X1) of the incremental encoder emulation IEE with the encoder input of the next b maXX drive (see example 1 in ►Figure 14◄ on page 35).
Pin assignment see ►Pin assignment IEE◄ on page 36,
Cable see ►Connecting cable IEE◄ on page 37.
- 4 Tighten the lock screws of the sub-D connector.
- 5 Install the connecting cable(s) in the switching cabinet according the standards.

5.4.3 Pin assignment IEE

Pin assignment of the Sub-D connectors (male) at the front of the incremental encoder emulation IEE:

Pin assignment



Pin No.	Meaning
1	Ground incremental encoder emulation
2	External power supply +5 V IEE
3	Incremental encoder emulation track 0
4	Incremental encoder emulation track -0
5	Incremental encoder emulation track B
6	not assigned
7	Incremental encoder emulation track -A
8	Incremental encoder emulation track A
9	Incremental encoder emulation track -B

5.4.4 Connecting cable IEE

The connection cable has to be manufactured by the user:

1 use following materials:

- cable: LiYCY LiYCY 3 x (2 x 0,14 mm²) + 2 x 0,34 mm² Cu-braiding.
- Sub-D connector: 9-pole, female (IEE side)
- e.g. Sub-D connector: 26-pole, male (b maXX 5000 side)
- cables from the incremental encoder emulation to the further control units must provide paired cables per track! (track -0/0, -A/A, -B/B)

2 connect

- the cable shield with the housing of the Sub-D male / Sub-D female connector
- the 9-pole female connector (IEE side) with the cable
- e.g. the 26-pole Sub-D male connector (b maXX 5000 side, pin assignment see Instruction handbook **b maXX 5000**) with the other end of the cable.

Blick auf Lötseite
View on solder pin side

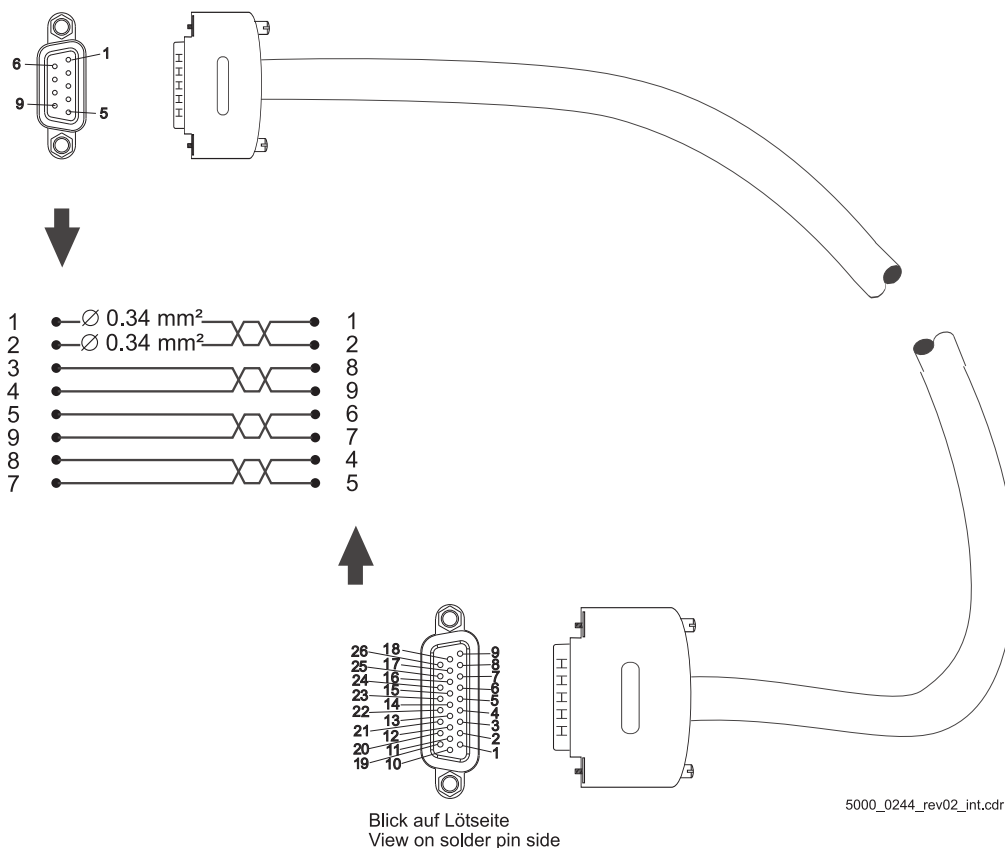


Figure 15: Connection cable IEE with b maXX 5000



NOTE!

The connection cable must be manufactured according the above mentioned instruction with the [Pin assignment IEE](#) on page 36!
The cable is not working with another pin assignment!

5.5 Installation SIE

5.5.1 Connection diagram SIE

Example 1:

- Set value SIE from encoder
- Signal SIE to master control

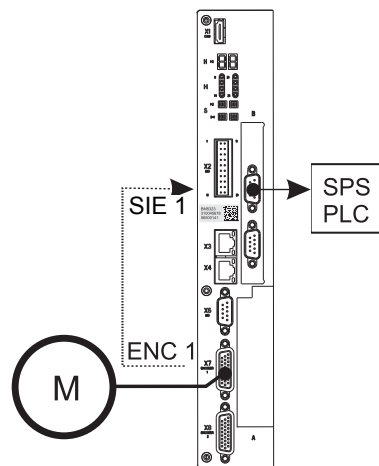


Figure 16: Connection diagram SSI encoder emulation SIE

5.5.2 Installation procedure SIE

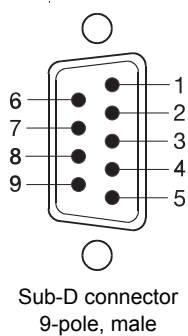
Depending on the desired application you now are able to connect the incremental encoder emulation with further system components (see [►Figure 16◄](#) on page 38).

- 1 Make sure that the **b maXX 5000** has been switched off voltage.
- 2 Connect an output of the SSI encoder emulation SIE with the encoder input of the master control (see example 1 in [►Figure 16◄](#) on page 38).
Pin assignment see [►Pin assignment SIE◄](#) on page 39,
Cable see [►Connecting cable SIE◄](#) on page 40;
- 3 Tighten the lock screws of the sub-D connector.
- 4 Install the connecting cable(s) in the switching cabinet according the standards.

5.5.3 Pin assignment SIE

Pin assignment of the Sub-D connectors (male) at the front of the SSI encoder emulation SIE:

Pin assignment



Pin No.	Meaning
1	Ground SSI encoder emulation
2	not assigned
3	not assigned
4	not assigned
5	DAT +
6	not assigned
7	CLK +
8	CLK -
9	DAT +



NOTE

The data and clock lines (DATA+/DATA- and CLK+/CLK-) are terminated on the SSI encoder emulation internal with 120 Ω. At the CNC-control you must still attach terminating resistors, if this hasn't been done by the manufacturer yet.

5.5.4 Connecting cable SIE

Cable length

The dependence of the maximum clock frequency to the cable length is shown in the diagram below:

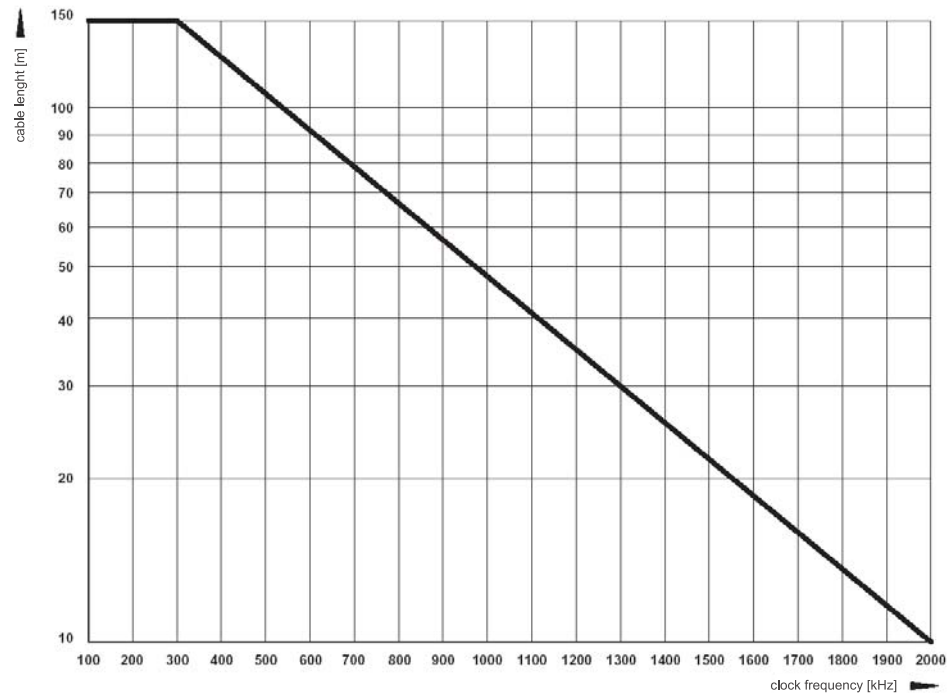


Figure 17: Cable length SSI encoder emulation

The connection cable can be used for following:

1 Use the following materials:

- Cable: data cable, paired drilled, Cu braiding, e.g. LiYCY 2 x (2 x 0.14 mm²) + 1 x 0.34 mm²).
- Sub-D connector: 9-pole, female (SSI encoder emulation side).
- Cables from SSI encoder emulation to CNC control must be paired drilled cables per track! (CLK+/CLK-, DATA+/DATA-).
See also [Pin assignment SIE](#) on page 39.

2 Connect

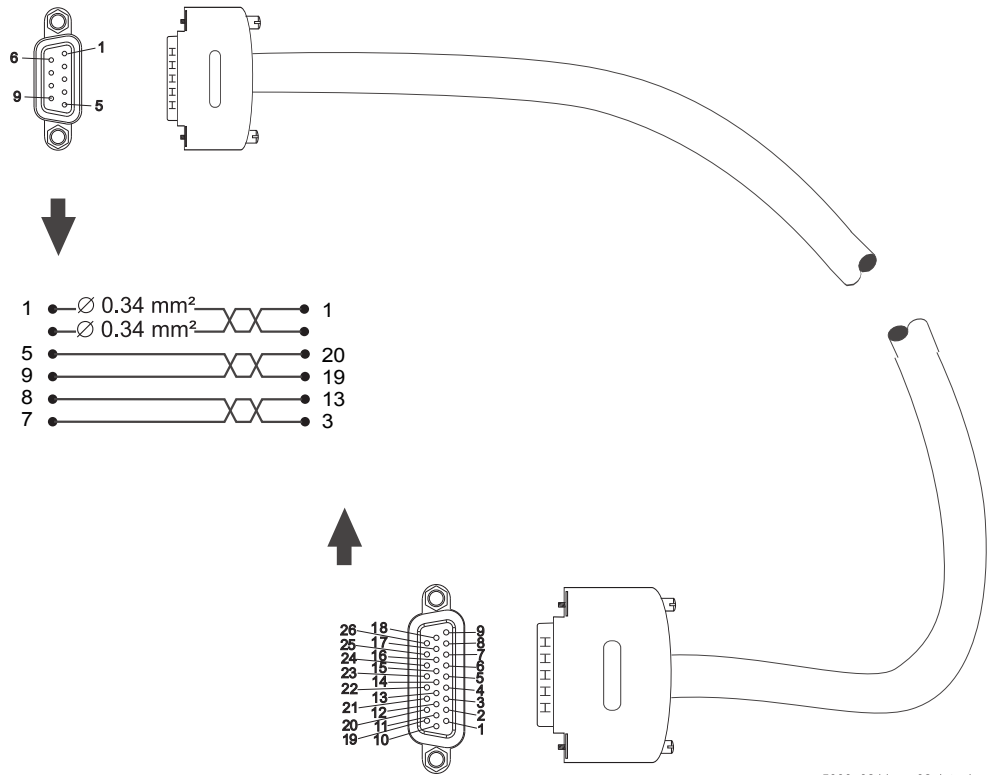
- the cable shielding with the housing of the Sub-D connector
- the 9-pole Sub-D connector with the cable
- e.g. the 26-pole Sub-D male connector (b maXX 5000 side, pin assignment see Instruction handbook **b maXX 5000**) with the other end of the cable.



NOTE

The data and clock lines (DATA+/DATA- and CLK+/CLK-) are terminated on the SSI encoder emulation internal with 120 Ω. At the CNC-control you must still attach terminating resistors, if this hasn't been done by the manufacturer yet.

View on solder pin side



5000_0244_rev02_int.cdr

View on solder pin side

Figure 18: Connection cable IEE with **b maXX 5000**

COMMISSIONING/OPERATION

The commissioning ensures that the **b maXX 5000 add-on module IEE/SIE** functions correctly. For further information on commissioning and parameterization see parameter handbook **b maXX 5000**.

Before commissioning, ensure that the following prerequisites are met:

- 1 Wiring of the **incremental encoder emulation IEE** or **SSI encoder emulation SIE** is done properly (IEE as shown in example 1 or 2 in [►Figure 14◄](#) on page 35 and SIE as shown in example 1 in [►Figure 16◄](#) on page 38.
- 2 The switching cabinet is closed properly and all the safety devices have also been put into operation.
- 3 The **b maXX 5000** is ready for use.

6.1 Safety notes

Basics



WARNING!

Risk of injury due to improper operation!

Improper operation can lead to severe personal injury or material damage.

Therefore:

- Perform all operational steps according to the details of these instruction handbook.
 - Before beginning any work, ensure that all coverings and protective devices are installed and are functioning properly.
 - The control cabinet in which the device is installed should be protected against contact with electrically live parts.
- Keep all doors of the control cabinet closed during operation.

6.2 Commissioning procedure IEE

The commissioning is divided into the following tasks:

- 1 Recognition of the **incremental encoder emulation IEE**
- 2 Configuring the **incremental encoder emulation IEE**
- 3 Function test

6.2.1 Recognition of the incremental encoder emulation IEE

While starting the device, the control unit reads out the identifier of the incremental encoder emulation (s) automatically.

After that, check with ProDrive whether the **incremental encoder emulation IEE** has been identified as correct:

- 1 Switch on **b maXX 5000**
- 2 Wait till the system has booted.
- 3 Open the window „**Startpage**“ in ProDrive.

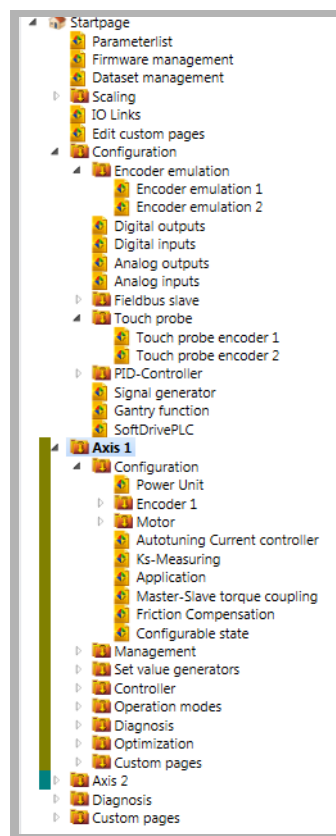


Figure 19: .ProDrive Navigation

4 Choose sub-menu „Axis 1/management“

and reset any faults/error messages eventually existing in the **b maXX 5000**. These errors might have been caused by faulty mounting (e.g. defective cable) or some mistake(s) in installation (e.g. supply voltage absent). Only after having eliminated the errors, the commissioning can be continued.

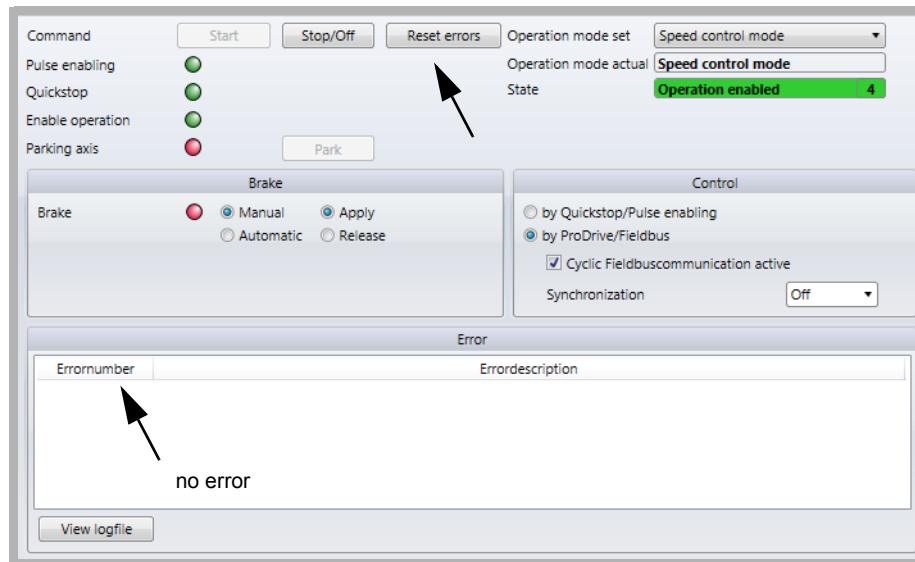


Figure 20: Drive management, reset errors

5 Activate encoder emulation in Configuration/Encoder emulation Choose „Encoder emulation 1“ or „Encoder emulation 2“

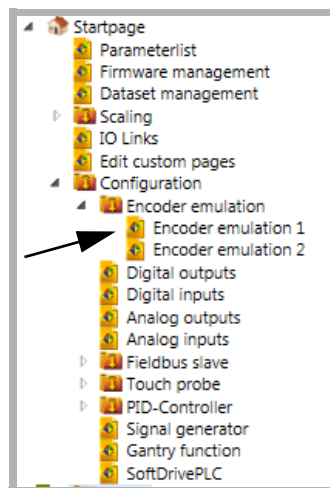


Figure 21: ProDrive, activate encoder emulation

If the **b maXX 5000** **b maXX 5000 add-on module IEE/SIE** has not been identified as correct or if it is not available, following error message is generated after activating the incremental encoder emulation.

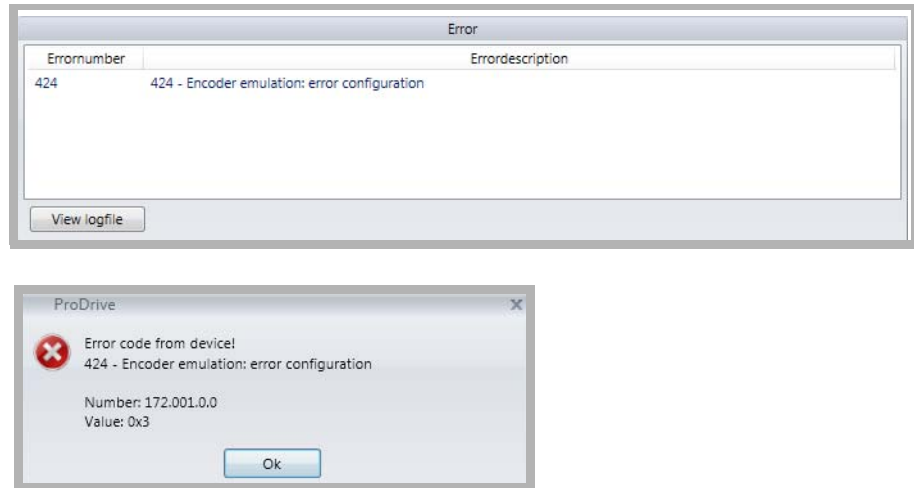


Figure 22: Drive management, IEE cannot be identified



NOTE

All error parameters of the incremental encoder emulation can be found in chapter [►Troubleshooting and fault correction◀](#) from page 59.

- Check the type code of the **b maXX 5000** whether the device provides an **add-on module IEE**.
Re-boot the device and check if the **add-on module IEE** is identified correctly, now.
- The **b maXX 5000** with **add-on module IEE** is damaged if it is still not identified. For replacement contact Baumüller Nürnberg GmbH.

6.2.2 Parameter setting IEE

The parameter setting influences the behavior of the incremental encoder emulation IEE while operating. The parameters are set in ProDrive.

- 1 Open ProDrive „Navigation“
- 2 Choose in configuration/Encoder emulation
„Encoder emulation 1“ or „Encoder emulation 2“

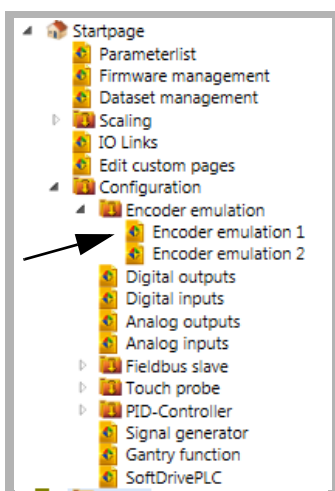


Figure 23: ProDrive, encoder emulation

- 3 In window „Encoder emulation 1“ all IEE relevant parameters referring to channel 1 (connector **X1**) can be set.

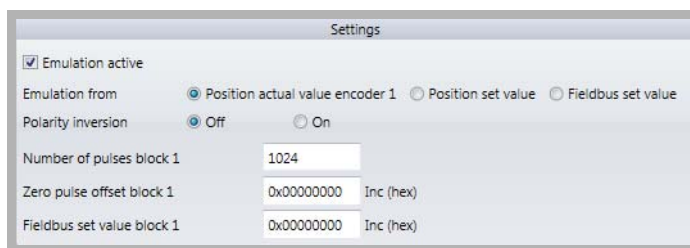


Figure 24: IEE relevant parameters channel 1

- 4 In window „Encoder emulation 2“ all IEE relevant parameters referring to channel 2 (connector **X2**) can be set.

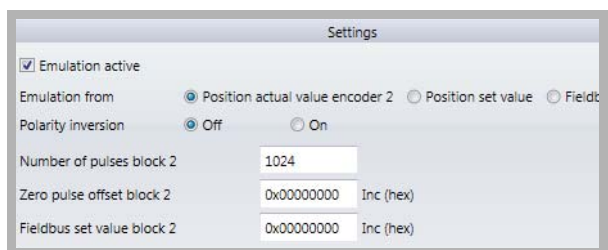


Figure 25: IEE relevant parameters channel 2

6.2 Commissioning procedure IEE

6.2.3 Function test IEE

The incremental encoder emulation can be tested with **b maXX 5000**, motor and encoder, only.

Requirements

- 1 Drive is in operating state (see parameter manual **b maXX 5000**). Encoder 1 connected with **X7 Encoder 1** for motor control.
- 2 **b maXX 5000** switched off again after successful first commissioning.
- 3 Connect output of **add-on module IEE** with input of **X8 Encoder 2** (connecting cable see [►Connecting cable IEE◄](#) auf Seite 37).

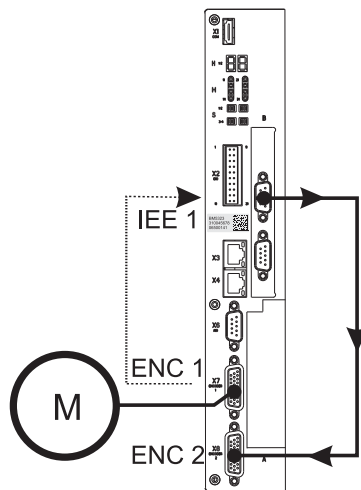


Figure 26: Connection incremental encoder and IEE



NOTE

If you want to use some other configuration, please turn to examples 2 and 3 in [►Figure 14◄](#) on page 35. In the following the above mentioned configuration is described, however.

- 4 Switch on **b maXX 5000**
- 5 Start ProDrive
- 6 Choose ProDrive Navigation, „Configuration/Encoder emulation 1“

- 7 All values and selections must be made according following ►Figure 27◄ in this window. The settings correspond with the signal of a square wave incremental encoder with 1024 increments.

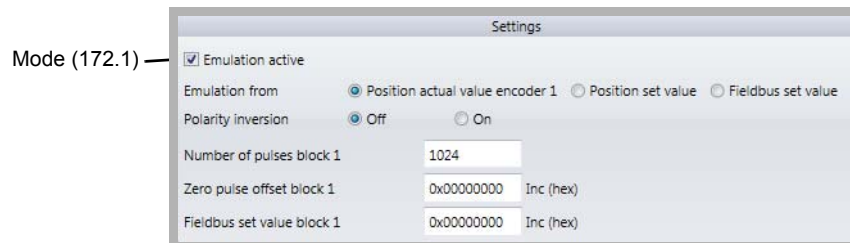


Figure 27: Encoder emulation 1 - settings

This corresponds with the following settings of the parameter list.

Parameter	Value
Mode (172.1)	0x0000 0001 (1 _{dez})
No. of increments (172.3)	1024 _{dez}
Zero pulse offset (172.4)	0x0000 0000 (0 _{dez})



NOTE

If the set value for the IEE is not generated by an encoder, as described in example above, the „Source“ (regarding 7) in window encoder emulation must be set to „Position set value“ or „Fieldbus set value“.

- 8 Choose in ProDrive Navigation „Configuration/Encoder/Encoder 2“
- 9 Set all values and selections according ►Figure 28◀ in this window.

Figure 28: Window Encoder 2 - Configuration

- 10 Choose in ProDrive Navigation „Set value generator/Ramp function generator“.

Figure 29: Window Ramp function generator

- 11 Set following parameters:
 - Ramp function generator input
 - Set value „10“ [%] beside „Input 32 bit“. Accept with „Enter“.

12 Click to the icon „Drive management“.

In addition window „Drive manager dialog“ appears.

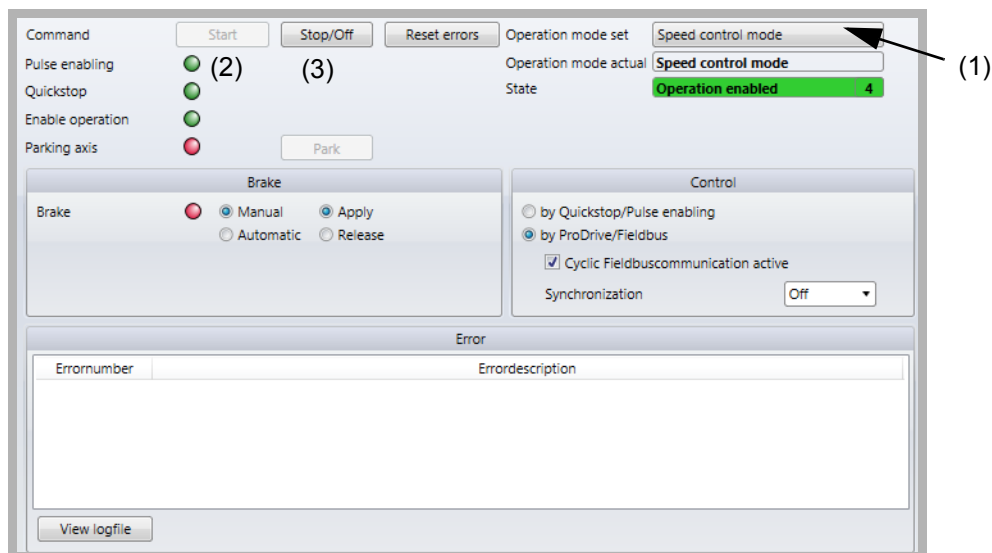


Figure 30: Ramp function generator - window with drive manager dialog

13 Select in scroll list (1) the operation mode „Speed control“

14 Switch on Pulse enable and No Quickstop

15 Click on button „Start“ (2) in drive management dialog.

The motor should rotate with 10 % of the maximum speed.

Control:

16 Choose in ProDrive Navigation „Configuration/Encoder/Encoder 1“.

17 In this window:
Speed smoothed: approx. 10 %



NOTE

Do not click on button „Stop“ (3) in the drive management dialog! First check if the speed actual value is transmitted to encoder 2 via the incremental encoder emulation IEE.

18 Choose in ProDrive Navigation „Configuration/Encoder/Encoder 2“.

19 In this window:
Speed smoothed: approx. 10 %



NOTE

If the generated signal of the **add-on module IEE** is processed in a higher-level control, please check the position values there.

Stop the drive after having checked the proper functioning of the **add-on module IEE**:

- ▶ Click on „Stop“ (3) in drive manager dialog menu
- ▶ Disable Quickstop release and pulse enable
- ▶ Switch off **b maXX 5000** and disconnect the connections
- ▶ Record the successful commissioning.

6.3 Commissioning procedure SIE

The commissioning is divided into the following tasks:

- 1 Recognition of the **SSI encoder emulation SIE**
- 2 Configuring the **SSI encoder emulation SIE**
- 3 Function test

6.3.1 Recognition of the SSI encoder emulation SIE

While starting the device, the control unit reads out the identifier of the encoder emulation automatically.

After that, check with ProDrive whether the **b maXX 5000 add-on module SIE** has been identified correctly:

- 1 Switch on **b maXX 5000**
- 2 Wait till the system has booted.
- 3 Check the window „**Startpage**“ in ProDrive.

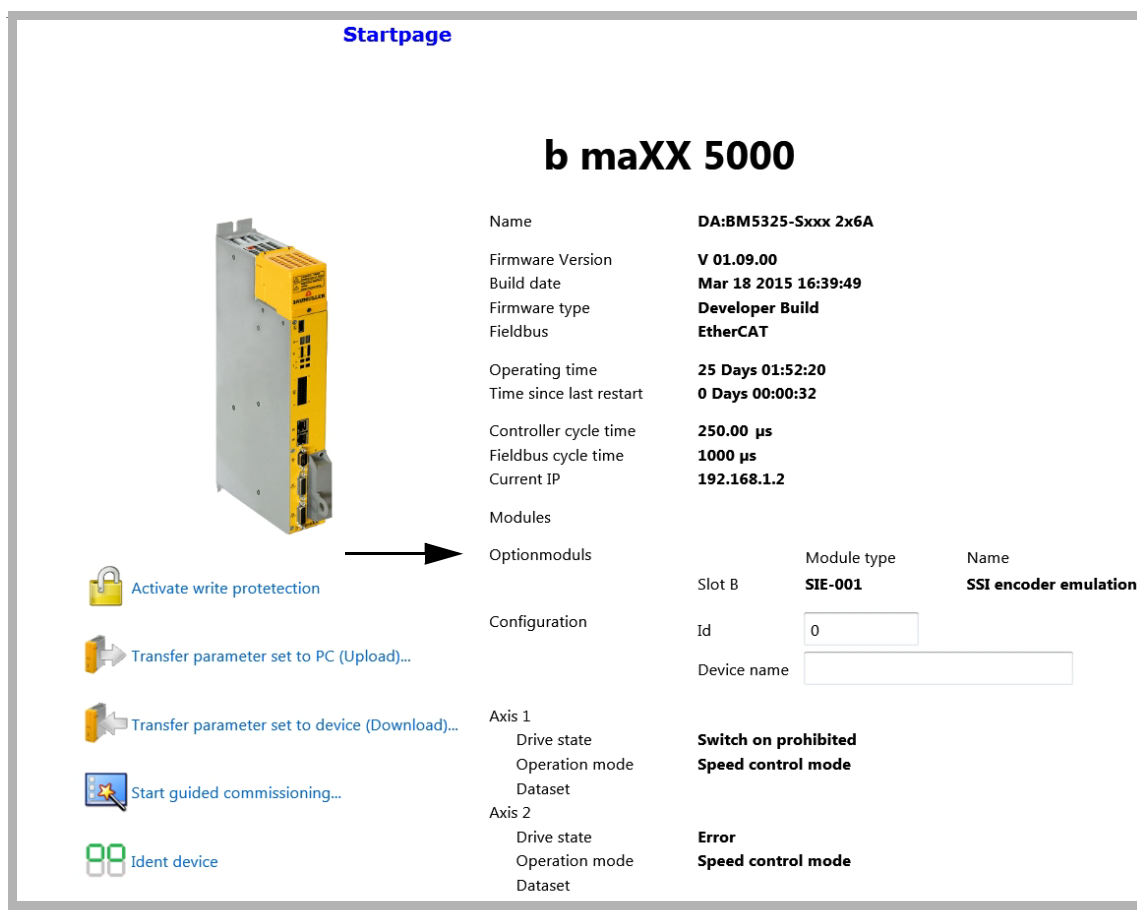


Figure 31: ProDrive Start page

4 Choose sub-menu „Axis 1/management“

and reset any faults/error messages eventually existing in the **b maXX 5000**.

These errors might have been caused by faulty mounting (e.g. defective cable) or some mistake(s) in installation (e.g. supply voltage absent). Only after having eliminated the errors, the commissioning can be continued.

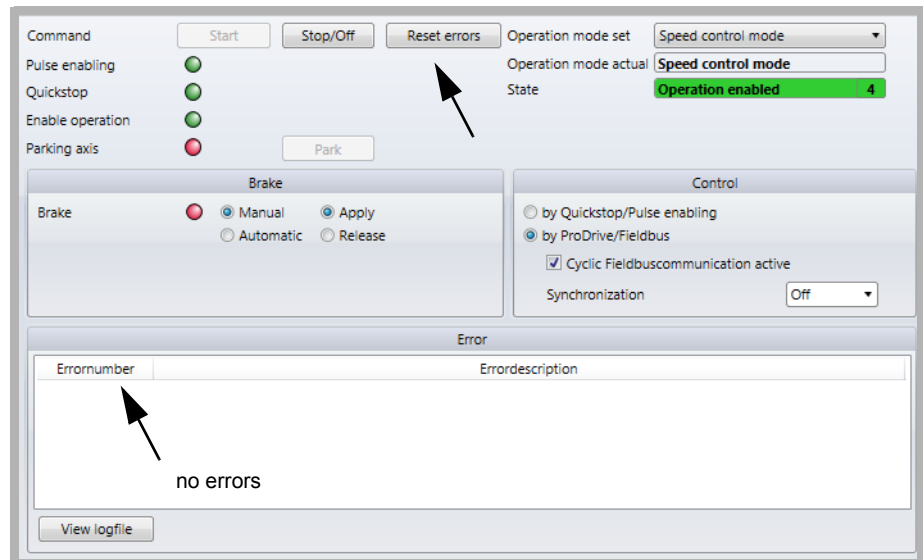
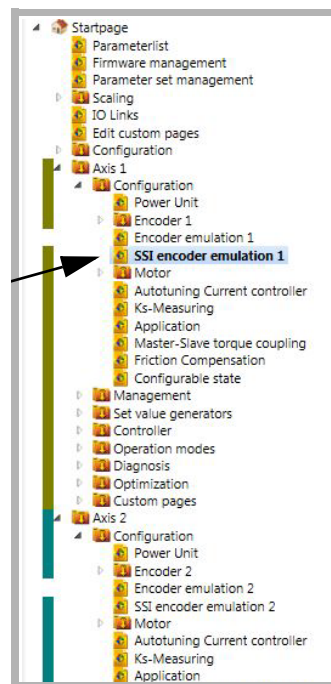


Figure 32: Drive management, reset errors

5 Activate encoder emulation e.g. in Axis 1/Configuration/SSI encoder emulation1



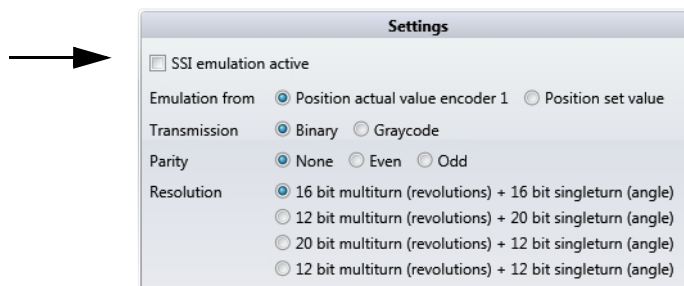


Figure 33: ProDrive, activate SSI encoder emulation

If the **b maXX 5000 add-on module IEE/SIE** has not been identified correctly or if it is not available, following error message is generated after activating the incremental encoder emulation.

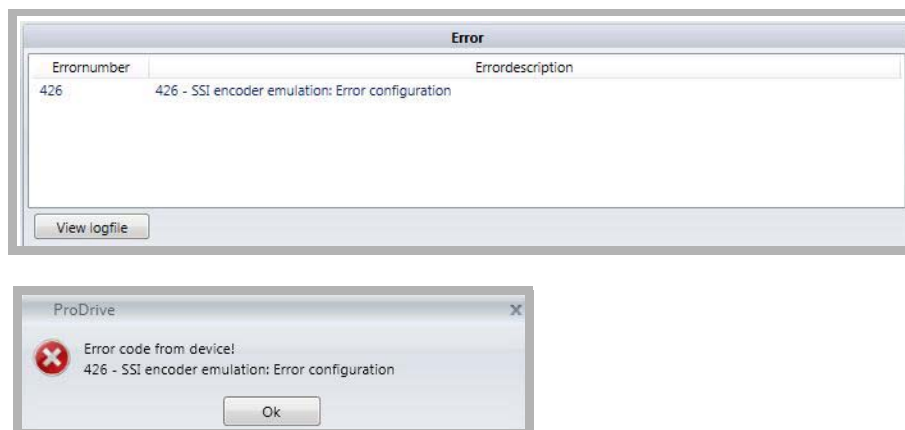


Figure 34: Drive management, SIE cannot be identified

**NOTE**

All error parameters of the SSI encoder emulation can be found in chapter [▶Trouble-shooting and fault correction](#) from page 59.

- Check the type code of the **b maXX 5000**, whether the device provides an **add-on module SIE**.
Re-boot the device and check if the **add-on module SIE** is identified correctly, now.
- The **b maXX 5000** with **add-on module SIE** is damaged if it is still not identified correctly. For replacement, contact Baumüller Nürnberg GmbH.

6.3.2 Parameter setting SIE

The parameter setting influences the behavior of the SSI encoder emulation SIE while operating. The parameters are set in ProDrive.

- 1 Open ProDrive „Startpage“
- 2 Choose in Axis 1/Configuration/SSI encoder emulation 1 or in Axis 2/Configuration/SSI encoder emulation 2

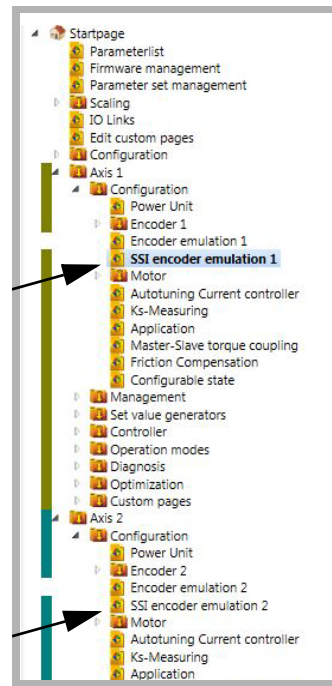


Figure 35: ProDrive, SSI encoder emulation

- 3 In window „Axis 1/SSI Encoder emulation 1“ all SIE relevant parameters referring to channel 1 (connector X1) can be set.

Settings	State
<input type="checkbox"/> SSI emulation active	State: deactivated
Emulation from: <input checked="" type="radio"/> Position actual value encoder 1 <input type="radio"/> Position set value	Timeout has appeared: <input type="radio"/>
Transmission: <input checked="" type="radio"/> Binary <input type="radio"/> Graycode	Transfer active: <input type="radio"/>
Parity: <input checked="" type="radio"/> None <input type="radio"/> Even <input type="radio"/> Odd	
Resolution: <input checked="" type="radio"/> 16 bit multiturn (revolutions) + 16 bit singleturn (angle)	
<input type="radio"/> 12 bit multiturn (revolutions) + 20 bit singleturn (angle)	
<input type="radio"/> 20 bit multiturn (revolutions) + 12 bit singleturn (angle)	
<input type="radio"/> 12 bit multiturn (revolutions) + 12 bit singleturn (angle)	

Figure 36: SIE relevant parameters channel 1

- 4 In window „Axis 2/SSI encoder emulation 2“ all SIE relevant parameters referring to channel 2 (connector **X2**) can be set.

Settings		State	
<input type="checkbox"/> SSI emulation active		State	deactivated
Emulation from	<input checked="" type="radio"/> Position actual value encoder 2 <input type="radio"/> Position set value	Timeout has appeared	<input type="radio"/>
Transmission	<input checked="" type="radio"/> Binary <input type="radio"/> Graycode	Transfer active	<input type="radio"/>
Parity	<input checked="" type="radio"/> None <input type="radio"/> Even <input type="radio"/> Odd		
Resolution	<input checked="" type="radio"/> 16 bit multiturn (revolutions) + 16 bit singleturn (angle) <input type="radio"/> 12 bit multiturn (revolutions) + 20 bit singleturn (angle) <input type="radio"/> 20 bit multiturn (revolutions) + 12 bit singleturn (angle) <input type="radio"/> 12 bit multiturn (revolutions) + 12 bit singleturn (angle)		

Figure 37: SIE relevant parameters channel 2

6.3.3 Function test SIE

The SSI encoder emulation can be tested with a CNC control unit, only.

TROUBLESHOOTING AND FAULT CORRECTION

7.1 Behavior in case of malfunctions

Basic information

**DANGER!****Risk of fatal injury from electrical current!**

Inevitably, when operating this electrical device, certain parts of it are energized with hazardous voltage.

Therefore:

- Pay heed to areas on the device that could be dangerous.

**WARNING!****Risk of injury due to improper fault correction!**

Therefore:

- Only qualified personnel may work on this device!
- Personnel that work with the **b maXX** device must be trained in the safety regulations and the handling of the device, and be familiar with the correct operation of it. In particular, reacting to error indications and conditions requires that the operator must have special knowledge.

7.2 Error detection

The fault can be caused by mechanical or electrical malfunctions.

LED

The occurrence of an error state is signaled by the lighting up of the red LED H14 or H24 on the front side of the housing.



NOTE!

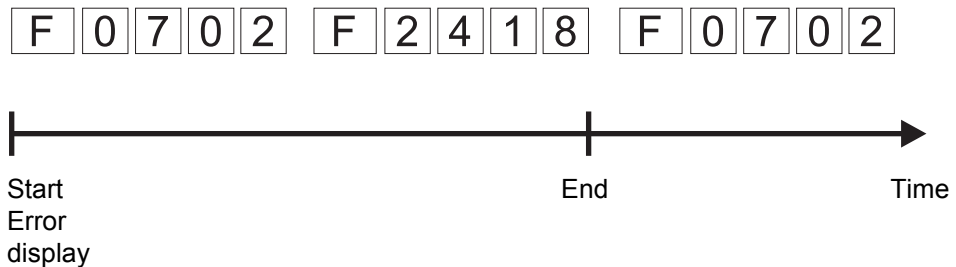
In case of warnings or errors without error reactions, the LEDs H14 or H24 **blink** „Malfunction“. Only error messages with error reaction will be signaled by **constant lighting up**.

7-segment display

In the status error the error numbers are shown in the display. Depending on the state of bit No. 16 in parameter **P135.1** (further information see parameter handbook **b maXX 5000 add-on module IEE/SIE**) all error messages (with/without error reaction) or warnings are displayed.

The display of an error code starts therewith, that „F“ is displayed for 1.5 s. Then the four characters of the error code are displayed. The separate characters are displayed for about 0.8 s, interrupted by a short break. If there are other errors, these are displayed in the same manner. The procedure is repeated as soon as all errors were displayed.

Example: Error 702 and 2418 are existing:



For further information on the subjects of error messages and error numbers, see „Parameter manual **b maXX 5000 add-on module IEE/SIE**“.

Operating software ProDrive

Furthermore the error message is shown in the operating software:



NOTE!

The controller software version and the operating software version must be compatible to use ProDrive with all functions.

7.3 Error handling



NOTE!

The device is provided with predefined error reactions. You are able to set the error reaction of the device in „Depending on settings“ in the column „Reaction“ marked error messages. An exception here are errors, which have to have an immediate pulse inhibit as a consequence. This error reaction can not be changed due to safety reasons.

7.3.1 Quit errors

If the red error LEDs H14 or H24 light up, at least one error exists.

Error acknowledgments cause all error messages to be reset. Individual acknowledgment of errors is not possible. An acknowledgment causes deletion of the errors, if deletion was possible on account of the error circumstances.

There are 4 methods of acknowledging an error:

- Via ProDrive:
Button “Quit errors” (either in the dialogue box “Device manager” or on the page “Device manager”).
That means, that you inform the device, that you have noted the error, that you have removed it or that you want to pass over it. Due to error reset all error messages are reset. An individual error reset is not possible. The button Quit errors causes a resetting of the error, in case the cause for the error message exists no longer.

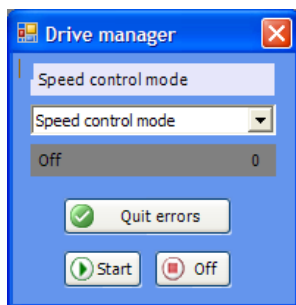


Figure 39: ProDrive Drive manager

- Via writing access to control word
- Via a digital input
- Via the pulse enable input:
Precondition is, that the drive is only controlled via the hardware inputs (that means that the motor guide is neither set via the operating software nor via another communication source). Furthermore the option “Quit error via pulse enable” must be active. With the first rising edge of pulse enable the errors then are reset. But the drive still does not start. Therefore you then need a second rising edge for the enable.

Additional data according the subject resetting of error messages is available in the „Parameter manual **b maXX 5000**“.

7.3.2 Error messages

In the column „Reaction“ the reaction of the system to the error is shown:

- „adjustable“ = the error reaction can be set via ProDrive (Window „Drive management“, toolbar button „Error reaction“).

IEE

Error No.	Error description	Reaction	Troubleshooting
424	Configuration error, further details in status P172.2 : <ul style="list-style-type: none"> Bit10: IEE add-on module is not available Bit11: Start after zero pulse selected and encoder is not an incremental encoder 	adjustable	<ul style="list-style-type: none"> Bit10: Use controller with IEE add-on module Bit11: Use incremental encoder for source encoder or select option „Start: immediately“.
425	Run time error, further details in status P172.2 : <ul style="list-style-type: none"> Bit 8: Output frequency to high add-on module IEE cannot generate the required number of pulses Cause: The product from set value change and no. of increments is too high Bit 9: Error in set value source IEE switches off, because of an error in set value source 	adjustable	<ul style="list-style-type: none"> Bit 8: Reduce no. of increments of IEE or reduce the drive speed, from which the set value is generated or reduce the set speed from the higher-level control according following formula: $f = n \cdot N$ f. no. of increments per sec n: Speed [revolution per sec.] N: No. of increments [inc/rev] $n_{\max} = f_{\max} / N$ Frequency limit=500 kHz, with N=10 000 inc/rev: $n_{\max} \leq 50 \text{ rev/s} \leq 3000 \text{ rev/min}$ Bit 9: Check set value source and correct problem

SIE

Error No.	Error description	Reaction	Troubleshooting
426	Configuration error, further details in status P173.2 : <ul style="list-style-type: none"> Bit12: Add-on module SIE is not available 	adjustable	<ul style="list-style-type: none"> Bit12: Use controller with SIE module
427	Run time error, further see status P173.2 : <ul style="list-style-type: none"> Bit 14: Time out The clock signal of the SSI master is missing 	adjustable	<ul style="list-style-type: none"> Bit 14: Check SSI encoder input and connection cables



Table of Figures

Pulse cycles, incremental encoder emulation IEE	21
Timing diagram 12/12 no parity	22
Timing diagram 12/12 parity	22
Timing diagram 16/16 no parity	22
Timing diagram 16/16 parity	23
Timing diagram 12/20 no parity	23
Timing diagram 12/20 parity	23
Timing diagram 20/12 no parity	23
Timing diagram 20/12 parity	23
Front view add-on module IEE	27
Front view add-on module SIE	28
Part number - front	29
Location of the type plate	30
Connection diagram incremental encoder emulation IEE	35
Connection cable IEE with b maXX 5000	37
Connection diagram SSI encoder emulation SIE	38
Cable length SSI encoder emulation	40
Connection cable IEE with b maXX 5000	41
.ProDrive Navigation	44
Drive management, reset errors	45
ProDrive, activate encoder emulation	45
Drive management, IEE cannot be identified	46
ProDrive, encoder emulation	47
IEE relevant parameters channel 1	47
IEE relevant parameters channel 2	47
Connection incremental encoder and IEE	48
Encoder emulation 1 - settings	49
Window Encoder 2 - Configuration	50
Window Ramp function generator	50
Ramp function generator - window with drive manager dialog	51
ProDrive Start page	53
Drive management, reset errors	54
ProDrive, activate SSI encoder emulation	55
Drive management, SIE cannot be identified	55
ProDrive, SSI encoder emulation	56
SIE relevant parameters channel 1	56
SIE relevant parameters channel 2	57
7-segment display: errors and warnings	60
ProDrive Drive manager	61



Table of Figures



Index

A

Accidents	16
Active mains rectifier unit	25
Axis unit	25
Axis unit safety	25

C

Caution	6
Commissioning procedure	44
Connection diagram	35
Customer service	8

D

Danger	6
Danger areas	31
DC link discharge time	14
Disposal	8

E

Electrical current, dangers of	14
Electrical data	20
Error detection	60
Error handling	61
Error messages	62

F

Fault correction	59
Fire fighting	15
Function test	48, 57

G

Guarantee provisions	8
----------------------	---

H

Hazardous situations	16
Hazards, special	14

I

Installation	33
Installation procedure	39
Instruction handbook, contents of	11

K

Key to symbols	6
----------------	---

L

Limitation of liability	7
-------------------------	---

M

Mains rectifier unit	25
Malfunctions, behavior	59
Modifications	11

N

Note	6
Notice	6

O

Operating personnel	13
Operation	43
Output signals	21

P

Parameter list	49
Part number	29
Personnel, qualified	13
Personnel, training	13
Pin assignment	36, 39
ProDrive, Start	44, 53

Q

Quit errors	61
-------------	----

R

Recognition of the IEE	44, 53
Residual energy, danger from	14

S

Safety equipment	16
Spare parts	8
Storage	
Temperature range	19
Switching cabinet	43

T

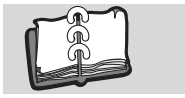
Technical data	19
Transport	
Climatic class	19
Temperature range	19
TTL square wave pulse cycles	21
Type code	31
Type plate	30

W

Warning	6
Warning notes	6

Z

Zero pulse	21
------------	----



Index



Survey of Revisions

Version	Edition	Changes
5.13030.01	10-Jan-2014	First issue
5.13030.02	18-Mar-2015	SSI encoder emulation SIE added
5.13030.03	12-Jul-2016	Error correction
5.13030.04	28-Nov-2019	Clock frequency SIE max. 2 MHz

Notes

be in motion

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